Continuous intraoperative neuromonitoring in minimally invasive video assisted thyroid surgery: first experience

Elias Karakas, Jakob Hinrichs, Beate Meier, Martin K. Walz, Pier Francesco Alesina

Department of Surgery and Center of Minimally Invasive Surgery, Kliniken Essen Mitte, Essen, Germany

Contributions: (I) Conception and design: E Karakas, PF Alesina; (II) Administrative support: MK Walz; (III) Provision of study materials or patients: E Karakas, B Meier; (IV) Collection and assembly of data: E Karakas, PF Alesina; (V) Data analysis and interpretation: E Karakas, J Hinrichs; (VI) Manuscript writing: All authors; (VII) Final approval of manuscript: All authors.

Correspondence to: Dr. Elias Karakas, PhD. Assistant Professor, University Marburg, Germany; Department of Surgery and Center of Minimally Invasive Surgery, Kliniken Essen-Mitte, Henrici street 92, Essen, Germany. Email: elias-karakas@web.de.

Background: Visual identification of the recurrent laryngeal nerve (RLN) is mandatory in thyroid surgery independent of the approach. Intermittent intraoperative neuromonitoring (ioNM) is broadly in open and minimally invasive thyroid surgery. However, the use of continuous intraoperative neuromonitoring (C-ioNM) has yet not been described for minimally invasive video-assisted thyroidectomy (MIVAT). The correct placement of the vagal electrode and the problem of its dislocation represent the limiting factor due to the narrow space. We describe the technique for correct electrode positioning and report on our first experiences with the C-ioNM in MIVAT.

Methods: C-ioNM was used in 9 patients eligible for MIVAT. To avoid dislocation of the electrode due to traction or interference with the electrode-wires during dissection both the wires and the electrode were pulled through an additional skin incision. MIVAT was then performed using a 5 mm 30° optical device and special instruments according to the original description from Miccoli. Video assisted hemithyroidectomy was performed in 3 patients, while 6 patients underwent total thyroidectomy.

Results: Video-assisted application of the vagal electrode and positioning of the wires via an additional access was feasible in all patients without complications. In 6 cases, the electrode-wires were pulled through an additional skin incision on the dominating side lateral to the sternocleidomastoid muscle. In two patients the wires were pulled through an additional incision in the midline below the surgical approach. In one patient the wires were diverted directly through the primary incision. A significant intermittent decrease of the electromyographic (EMG) amplitude was observed in one patient. However, postoperative RLN palsy rate was zero.

Conclusions: C-ioNM in MIVAT is feasible. An additional skin incision is helpful to avoid electrode dislocation. Traction of the thyroid lobe during thyroid lobe mobilization does not seem to affect RLN function. However, more data has to be collected to definitely estimate the significance of C-ioNM in MIVAT.

Keywords: Neuromonitoring; continuous; thyroid surgery; minimally invasive

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Introduction

Intraoperative neuromonitoring (iONM) is used in various fields. IONM was developed to monitor the functional neural integrity, with the aim to detect or prevent impending/imminent damage due to indirect or direct nerve injury at an early stage. Alteration of the neural response during surgery may lead to a change in operative strategy to prevent further and potentially irreversible damage. iONM is widely used in thyroid and parathyroid surgery. Nevertheless, visual identification of the recurrent laryngeal nerve (RLN) remains the gold standard. Even if intermittent iONM does not reduce the rate of postoperative RLN palsy, it enhances identification of the RLN and predicts in about 2/3 of the cases the findings of postoperative laryngoscopy (1). After its introduction in thyroid surgery, the concept of two-stage thyroidectomy in case of loss of signal (LOS) after dissection of the RLN on the first side has been proposed and strongly recommended at least in selected cases to avoid bilateral RLN palsy (2,3).

Continuous iONM (C-iONM), considered as the next step in nerve monitoring, provides real-time RLN evaluation during surgery and may help to detect impending injury of the RLN earlier than intermittent electromyographic (EMG) monitoring. Currently, promising data are available advising fewer permanent vocal fold palsies after thyroid surgery using C-iONM compared with I-iONM (4). However, all published data regarding C-iONM in thyroid surgery refer to conventional open surgery, which allows an easy application of the vagal electrode and the electrode wires that can easily be inserted through the primary incision (5-8).

The use of C-iONM during video-assisted thyroidectomy is barely described because of the limitations due to the narrow space available for the application and correct placement of the vagal electrode.

As a referral center in endocrine surgery with a large experience in the field of minimally invasive thyroid surgery we report on our first experiences with the C-iONM during minimally invasive video-assisted thyroidectomy (MIVAT).

Methods

To evaluate the feasibility and applicability of C-iONM in MIVAT we identified 9 patients. Preoperative clinical data was summarized in Table 1.

<table>
<thead>
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<th>Clinical parameters</th>
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<td>Age [years, median, range]</td>
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<tr>
<td>Indication for surgery (n)</td>
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<tr>
<td>Suspicious solitary nodule</td>
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<tr>
<td>Graves’ disease</td>
<td>2</td>
</tr>
<tr>
<td>Thyroid volume (mL, median, range)</td>
<td>15 [14–25]</td>
</tr>
</tbody>
</table>

MIVAT, minimally invasive video-assisted thyroidectomy.

Written informed consent was obtained and the research was conducted according to the principles of the Declaration of Helsinki.

Operative technique

Surgery was performed on the basis of the technique first described by Miccoli (9). After a 2-4 cm skin incision above the sternal notch, the cervical linea alba was opened and the thyroid separated from the strap muscles. The surgical field was maintained using conventional retractors. The muscles were retracted laterally while the thyroid lobe was retracted medially. Further dissection was performed under video-assistance using a 5 mm 30° camera (Karl Storz GmbH® Tuttlingen, Germany), leading to a 5-fold magnification of the structures and special instrumentation including slim scissors, spatula and a spatula shaped aspirator. Haemostasis was achieved with bipolar devices or ligature. The first step was visual identification of the vagus nerve and stimulation with a bipolar handheld stimulation probe (4 Hz, 200 μs, 1 mA; Dr. Langer Medical GmbH®, Waldkirch, Germany). The vagus nerve was separated from the surrounding tissue and a vessel loop was wrapped around the nerve (Figure 1). The electrode wires were either pulled through an additional skin incision on the dominating side lateral to the sternocleidomastoid muscle or through an additional incision in the midline below the cervical approach (Figure 2A,B). Then the saxophone-shaped single-channel electrode (3 Hz, 200 μs, 1 mA Dr. Langer Medical®,
The vagus nerve is identified and a vessel loop is wrapped around the nerve (Figure 1). After correct placement of the electrode and baseline EMG recording, surgery continued with the dissection of the upper pole vessels as usual. To expose and dissect the upper pole vessels, the thyroid lobe was retracted downward. After transection of the upper pole vessels, the lobe was extracted through the primary skin incision and the RLN and parathyroid glands were identified and preserved. The dissection of the lobe was then completed under direct vision.

General anesthesia was maintained by complete intravenous application of Propofol (6–12 mg/kg/h) in combination with remifentanil (0.1 μg/kg/min). No neuromuscular blocking agents were allowed during surgery. EMG amplitude and latency changes were recorded especially with regard to potential reduction of the EMG amplitude >50% and/or increase in latency by >10% which was defined as LOS resulting in possible RLN damage (10).

Six patients were scheduled for total thyroidectomy because of Graves’ disease (n=2) or multinodular goiter (n=4) and three for lobectomy due to a suspicious solitary thyroid nodule. All patients underwent pre- and postoperative laryngoscopy. Preoperative characteristic of the patients, intraoperative data and postoperative complications were collected prospectively. Patients were generally discharged on the second postoperative day.

Figure 1 The vagus nerve is identified and a vessel loop is wrapped around the nerve.

Figure 2 (A,B) Central 2 cm large skin incision for MIVAT. The C-ioNM wires were pulled through an additional skin incision lateral to the sternocleidomastoideus muscle (A) or below the sternal notch (B). MIVAT, minimally invasive video-assisted thyroidectomy; C-ioNM, continuous intraoperative neuromonitoring.

Figure 3 Saxophone shaped electrode placed around the right vagus nerve under direct view.
Results

All thyroid operations were completed as planned. The mean operating time was 98±13 min for lobectomy and 93±13 min for total thyroidectomy, including the electrode placement time.

In 6 patients, the electrode-wires were pulled through the additional skin incision on the dominating side lateral to the sternocleidomastoid muscle. In two patients, the wires were pulled through the additional incision in the midline below the surgical approach, and in one patient, the wires were diverted directly through the primary incision.

There were no complications during the placement of the electrode wires via the additional access. After a short learning curve the median time until correct placement of the vagal electrode was 5 minutes (range, 5–20 minutes).

Replacement of the electrode during surgery was not necessary, however in one patient with the electrode wires diverted through the primary incision we observed a dislocation of the vagus electrode during surgery and changed to intermittent nerve monitoring.

Intermittent EMG amplitude decrease >50% and increase of latency >10% was observed in one patient during the mobilization of the thyroid lobe. However, postoperative rate of RLN palsy was zero.

Discussion

Whereas almost all data published regarding C-ioNM in neck surgery refer to open surgery with large skin incisions, we were able to proof feasibility and applicability of C-ioNM in MIVAT. This study describes the use of C-ioNM during MIVAT with an additional lateral small skin incision for the first time.

The minimally invasive approach in thyroid surgery leads to an optimized cosmetic result and has gained worldwide acceptance. Two major limitations for C-ioNM during MIVAT have to be mentioned. The correct positioning of the vagal electrode through the small skin incision under video assistance is demanding due to the narrow working space. The diversion of the electrode wires through the primary skin incision leads to a high rate of electrode dislocation during the procedure especially when pulling the thyroid lobe through the small skin incision.

In contrast to another technique described, in which the electrode wires are diverted either directly through the primary skin incision through and between the thyroid lobe medially and the strap muscles laterally or a modified way through the primary skin incision between the space of the sternothyroid and sternocleidomastoid muscle (11), we investigated the ability to pull the electrode wires through an additional lateral skin incision. This maneuver turned out to be feasible, helpful and safe to avoid electrode dislocation during surgery. The only case of electrode dislocation we observed in this series was the case with the electrode wires diverted through the primary incision.

Traction is reported to be the most common cause of RLN palsy (12,13) and C-ioNM has the potential advantage to recognize threatening nerve lesions by monitoring nerve function nearly in real time.

Published data have shown that impending nerve injury can be recognized by EMG changes as combined events affecting amplitude and latency (10,14). Interestingly, several study groups report on amplitude variations and reduction up to 70% between animals and between the two nerves in the same animal, even if traction force was kept constant (15,16).

In our study we observed EMG amplitude changes of >50% and changes in latency of >10% in only one patient during the extraction of the thyroid lobe, which did not affect the surgical strategy and did not lead to a RLN palsy.

The rate of RLN injuries in specialized endocrine centers is low and the use of intermittent ioNM is not able to additionally reduce the incidence of RLN palsy. However, the use of ioNM allows inexperienced surgeons to perform a safe operation with a complication rate comparable to that obtained under supervision of an experienced surgeon (17) and ioNM is reported to be useful in challenging redo surgery in the neck (18).

Instead, the data published on C-ioNM seems to show that its use is associated with a significant lower permanent RLN palsy rate (4). If this data will be confirmed in further studies, C-ioNM will become undeniable in thyroid surgery also if performed by a minimally invasive approach.

Conclusions

In this study we showed that C-ioNM is feasible and safe during MIVAT. An additional skin incision to pull through the electrode wires is necessary to avoid electrode dislocation during surgery. Traction of the thyroid lobe after transection of the upper pole vessels during mobilization does not seem to affect RLN function.

However, more data have to be collected to definitely estimate significance of C-ioNM in minimally invasive thyroid surgery.
Acknowledgements

None.

Footnote

Conflicts of Interest: The authors have no conflicts of interest to declare.

Ethical Statement: Written informed consent was obtained and the research was conducted according to the principles of the Declaration of Helsinki. No concerns were raised from the ethical point of view (no approval number available).

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